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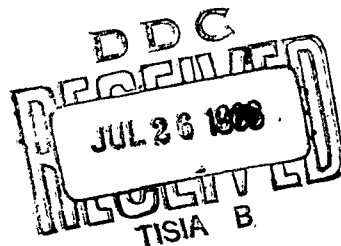
# TECHNICAL MEMORANDUM

(TM Series)

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General Purpose

Satellite Computer Program Descriptions

Milestone 11

Time Check (TCK)

by

C. M. Chiodini

14 November 1962

Approved

B. G. Ciaccia

SYSTEM

DEVELOPMENT

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## SUBROUTINE IDENTIFICATION

- A. Title: TCK, Time Check, Identification G31, Mod. 01.
- B. Programmed: C. Murray, 13 July 1961, Lockheed Missiles and Space Division.
- C. Documented: C. M. Chiodini, 11 October 1962, System Development Corporation.

## PURPOSE

TCK deletes Tracking Data Points from the Constant Pool of the user function when the component times (T) are out of range or out of order.

## USAGE

- A. Calling Sequence.

L	SLJ	4	TCK
L+1	NOP		T
	NOP		AZ
L+2	NOP		EL
	NOP		SR
L+3	Normal return		

where:

T, AZ, EL, and SR are the beginning addresses of the tracking point components in the Constant Pool of the user function.

- B. Input Parameters.

1. A Register: LIST TEST value. A zero value will result in an off-line listing of the deleted times modulo 86400 seconds. Any non-zero value in LIST TEST will bypass the output.
2. Q Register: The pass duration in floating point seconds if UHF Data (Format=3) is to be processed.
3. NT: The number of tracking data points. This integer item is in the Reference Pool.
4. FORMAT: The type of radar. This integer item is in the Reference Pool.

<u>ITEM VALUE</u>	<u>DATA TYPE</u>
0	Mod 2
1	Doppler (Range-Rate)
2	TLML8
3	UHF

5. Tracking data points in the Constant Pool of the user function.

<u>SYMBOL</u>	<u>DEFINITION</u>	<u>FORMAT</u>	<u>UNITS</u>
T	Machine Time	Floating Point	Seconds
AZ	Azimuth	Floating Point	Radians
EL	Elevation/Range	Floating Point	Radians
SR	Slant Range Rate	Floating Point	Feet

C. Output.

1. The number of valid tracking data points, NT in the Reference Pool.
2. A set of revised points in the Constant Pool of the user function with bad points deleted.
3. An off-line listing (on Tape 3) of component Times in the tracking data array which were out of range or out of order. This output is optional, dependent upon the LIST TEST value.
4. User Functions.

ASCENT	DATLAP
CCOORD	NEURN
COMPARE	REDUCE
REENTRY	

METHOD

TCK is subdivided into 4 major program regions and an internal output subroutine. In the first region, TCK obtains input parameters from the user function calling sequence and modifies program steps for data point processing. It also determines the type of data to be processed, and defines a delta time for the given type. In the second region, TCK determines if the component times in the point array are in

ascending order. A point whose time is out of order is deleted from the tracking data point array in the Constant Pool of the User Function. TCK then checks for missing data points in the third program region and computes a time range, upper and lower limit, for each of the component times in the array. A final range is then formulated and any point whose time is not within the range is also deleted from the tracking data set. An output of the rejected time is written on tape, if requested, by the TCK internal output subroutine.

#### RESTRICTIONS

- A. The maximum number of points processed by TCK is contingent upon the Constant Pool tracking data allocation of the user function. The minimum number of points processed by TCK is two (2). If there is one point or less, TCK exits to the normal return address of the user function.
- B. Index registers 1, 5 and 6, pre-TCK entry values, are saved and restored at the completion of TCK operation.
- C. The Reference Pool items NT and FORMAT must be set prior to TCK operation. TCK uses NT to process all the data points and resets this item with the number of valid points upon completion. FORMAT (radar data type) is used by TCK to define a delta time ( $\Delta t$ ) for range determination and to ascertain if Doppler (FR and T) data or other type data points (SR, EL, AZ, and T) are to be processed.
- D. Since the component times in the tracking data point array must be in machine time, routine TEDIT, or a similar conversion routine, must be executed prior to TCK. TEDIT converts time from fixed point integer seconds to floating point machine time.
- E. The components of the tracking data point (T, AZ, EL, SR), must be in parallel structured tables in the Constant Pool of the user function.
- F. Two cells of COMMON are used in TCK operation.

G. The following subroutines are used by TCK:

FIX	OUTERR
FLOAT	OUTPUT
SUBERR	

#### TIMING

TCK program execution time is dependent upon: (1) the number of points processed, (2) the number of times within a given range, (3) the number of times outside a given range, (4) the number of times not in ascending order, and (5) the off-line list option. Approximately 1146.7 milli-seconds are required to process 200 valid tracking data points by TCK.

#### STORAGE REQUIREMENTS

##### A. Program Allocation.

Program Steps	135 cells
Storage	12 cells
Constants	<u>8</u> cells
TOTAL	155 cells

##### B. Program Storage.

<u>TAG</u>	<u>DESCRIPTION</u>
TCK901	Delta Time ( $\Delta t$ )
TCK902	Current Upper Limit
TCK903	Current Lower Limit
TCK904	Final Upper Limit
TCK905	Final Lower Limit
TCK906	Time Factor
TCK907	Count
TCK908	FORMAT value -1
TCK950	Program loop control to process all points in the data array.
TCKMPTS	Number of missing points
TCKSUM	Summation of mission points in the data array
TCKXRI	Relative position of a given time in the array

## C. Program Constants.

<u>TAG</u>	<u>DESCRIPTION</u>	<u>FORMAT</u>	<u>UNITS</u>
TCK951	Output list heading "TIME CHECK"	Binary Coded Decimal	
F1	Constant used in Missing Point Check(1.0)	Floating Point	
F2	Delta Time for Doppler data (2.0)	Floating Point	Seconds
F4	Delta Time for TLM18 or MODII data (4.0)	Floating Point	Seconds
F.5	Time increment (.5)	Floating Point	Seconds
LIMPTS	Limit for the number of missing point between successive times in the array (15.0)	Floating Point	
MZERO	Program Mask used to complement arithmetic values (7777 7777 7777 7777)	Octal	
D86400	Number of seconds in a 24 hour period (86400)	Fixed Point Integer	Seconds

## TRANSFER FUNCTION

## A. Terms and Definitions

1. i, j, k, l, m, p = indexers to specify any given point in the tracking data array (relative position). In general, these indexers have a range from 0 to NT-1 or as indicated.
2. NT = Number of tracking data points
3. FORMAT = Type of radar
  - 0 = Mod II
  - 1 = Doppler (Range-Rate)
  - 2 = TLM18
  - 3 = UHF

4.  $t$  = Delta time  
       Doppler = 2 seconds  
       Mod II, TLM18 = 4 seconds  
       UHF =  $\frac{\text{Pass Duration}}{NT-1}$  seconds

5. Tracking Data Point

$T$  = Time  
 $EL$  = Elevation (Range-Rate for Doppler)  
 $AZ$  = Azimuth (not used for Doppler)  
 $SR$  = Slant Range (not used for Doppler)

6. FLL = Final Lower Limit

7. FUL = Final Upper Limit

8. LIMPTS = Limit for number of missing points  
       (See Program Constants)

9. LISTTFST = Output List Option Indicator

B. Ascending Order Check. Perform until points are in order.

1. If  $T_{i+1} > T_i$  for all  $i$  ( $i=0, 1, \dots, NT-2$ ) Points are in order.

2. If  $T_{i+1} \leq T_i$  for any  $i$  A point is out of order

Find worst point  $K > j$  such that: Eliminate point  $K$

$$\left| \sum_{p=0}^{p=NT-1} \alpha_{pk} + K - (NT-1) \right| \geq \left| \sum_{p=0}^{p=NT-1} \alpha_{pj} + j - (NT-1) \right| \quad (\text{See Note})$$

where:  $\alpha_{pk} = 1$  if  $T_p > T_k$

$\alpha_{pk} = 0$  if  $T_p \leq T_k$

$\alpha_{pj} = 1$  if  $T_p > T_j$

$\alpha_{pj} = 0$  if  $T_p \leq T_j$

C. Range Determination and Check

1. Compute Range (FLL, FUL)

$$\text{Find } i > l \text{ such that } \sum_{j=0}^{j=NT-1} \beta_{ij} \geq \sum_{j=0}^{j=NT-1} \beta_{lj}$$

where:  $\beta_{ij} = 1$  if  $T_i - [.5 + \Delta t(i + Dsum)] < T_j \leq T_i + \Delta t(NT - 1 - i)$

$\beta_{ij} = 0$  otherwise

$\beta_{lj} = 1$  if  $T_l - [.5 + \Delta t(l + Dsum)] < T_j \leq T_l + \Delta t(NT - 1 - l)$

$\beta_{lj} = 0$  otherwise

$Dsum = \sum_{p=0}^{p=NT-2} dp$

$dp = 0$  if  $\frac{T_{p+1} - T_p}{\Delta t} - 1 > LIMPTS$

$dp = \frac{T_{p+1} - T_p}{\Delta t} - 1$  otherwise

a. If  $\sum_{j=0}^{j=NT-1} \beta_{ij} > \sum_{j=0}^{j=NT-1} \beta_{lj}$

Set:

$FLL = T_i - \Delta t(i + Dsum)$

$FUL = T_i + \Delta t(NT - 1 - i)$

b. If  $\sum_{j=0}^{j=NT-1} \beta_{ij} = \sum_{j=0}^{j=NT-1} \beta_{lj}$

Set:

$FLL = T_l - \Delta t(l + Dsum)$

$FUL = T_l + \Delta t(NT - 1 - l)$

2. Examine all points K

a. If  $FLL \leq T_k < FUL$

Point is in range.

b. If  $T_k < FLL$

Point is out of range.

Eliminate point K

(See Note)

or

$T_k \geq FUL$

Note: To eliminate point K

1. For  $m = K, K+1, \dots, NT-2$

a. If  $FORMAT = 1$

Set  $T_m = T_{m+1}$

$EL_m = EL_{m+1}$

b. If  $\text{FORMAT} \neq 1$

Set:  $T_m = T_{m+1}$

$EL_m = EL_{m+1}$

$AZ_m = AZ_{m+1}$

$SR_m = SR_{m+1}$

2. Reduce number of points

Set:  $NT = NT - 1$

3. If  $\text{LISTTEST} = 0$

List Time Eliminated  
off-line

#### VALIDATION TESTS

A test routine was written to provide input parameters to TCK and to output program results utilizing the COP Defines function. Ten tests were run consisting of a set of ten tracking data points for each type of data. In addition, several tests of 200 points were made to validate the missing point computations in TCK. After analysis of the test results, given data points were deleted from the tracking data array when a component time was out of order or out of the computed range. In a like manner, no points were rejected when the time interval between successive points was other than nominal and when the number of missing points was not greater than the program limit of 15 points. The program option to list "bad" times was exercised and operated correctly. The number of points (NT in the Reference Pool) was also updated correctly for each point rejected by TCK.

#### REFERENCE

A. LMSD-447578, 1604 Systems Manual

<u>PROGRAM</u>	<u>PAGE</u>
OUTPUT	45.01.01
COMPARE	45.10.01
OUTERR	50.05.01
SUBERR	50.06.01
CCOORD	55.05.21
REDUCE	55.25.29

<u>PROGRAM</u>	<u>PAGE</u>
TCK	55.35.11
TEDIT	55.50.25
DATLAP	55.60.01

B. Manual of Operating Instructions for Satellite Control Computer Programs.

<u>PROGRAM</u>	<u>PAGE</u>
ASCENT	3.2.1
NBURN	3.4.1
REENTRY	3.6.1

C. TM-(L)-715/008/00, General Purpose Satellite Control Program Description of FIX.

D. TM-(L)-715/009/00, General Purpose Satellite Control Program Description of FLOAT.

## FLOW CHART

## Terms and Definitions:

$i, j, k$  = An integer to specify any given element in the tracking data array (relative position). This value has a range of 0 through  $NT-1$  and is set as indicated.

$NT$  = Number of tracking data points

$\Delta t$  = Delta Time

Doppler = 2 seconds

MODII, TLM18 = 4 seconds

$$UHF = \frac{\text{Pass Duration}}{NT-1} \text{ seconds}$$

## Tracking Data Point

$T$  = Time

Doppler (Range-Rate)

$EL$  = Elevation

MODII

$AZ$  = Azimuth

TLM 18

UHF

$SR$  = Slant Range

$D$  = The number of missing points between two successive times.

$D_{SUM}$  = The summation of missing points in the tracking data set.

$TF$  = Time Factor

$CLL$  = Current Lower Limit

$CUL$  = Current Upper Limit

$COUNT_p$  = Previous Count

$COUNT_e$  = Current Count

$(T > CLL)$  = An integer denoting the number of Times in the array which are greater than the current lower limit.

$(T > CUL)$  = An integer denoting the number of times in the array which are greater than the current upper limit.

$NTGT_1$  = An integer denoting the number of Times in the tracking data set which are greater than a given time in the set( $T_1$ ).

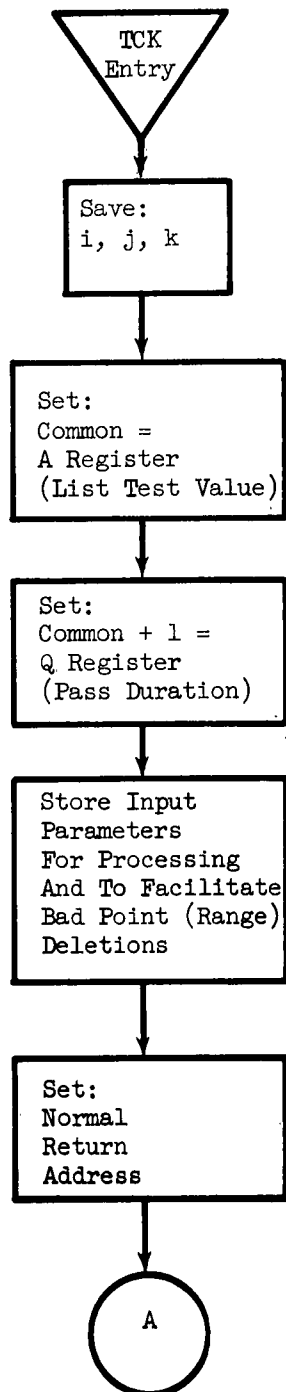
$FLL$  = Final Lower Limit

$FUL$  = Final Upper Limit

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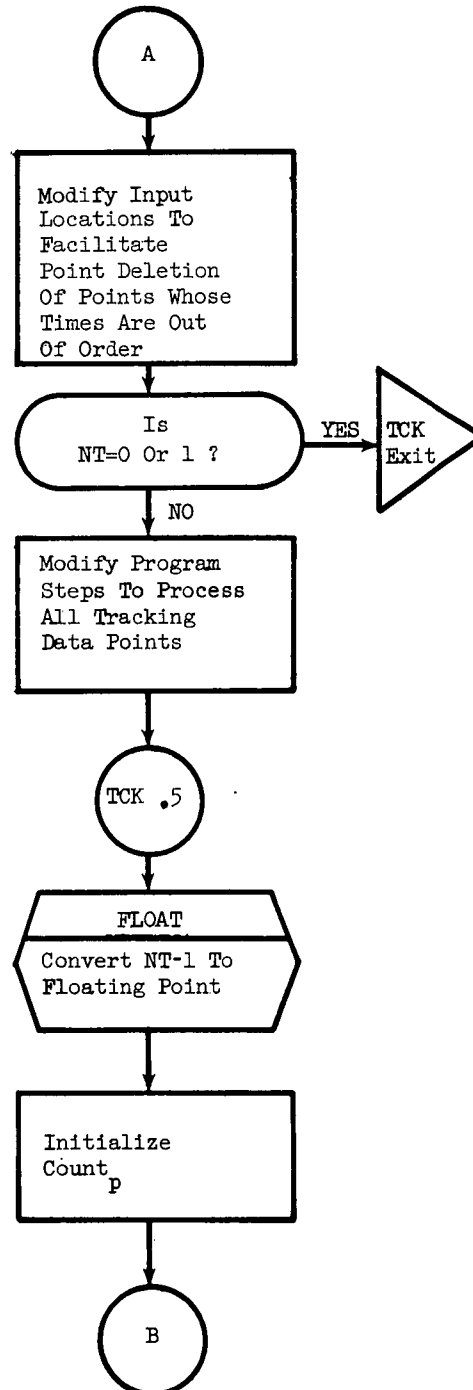
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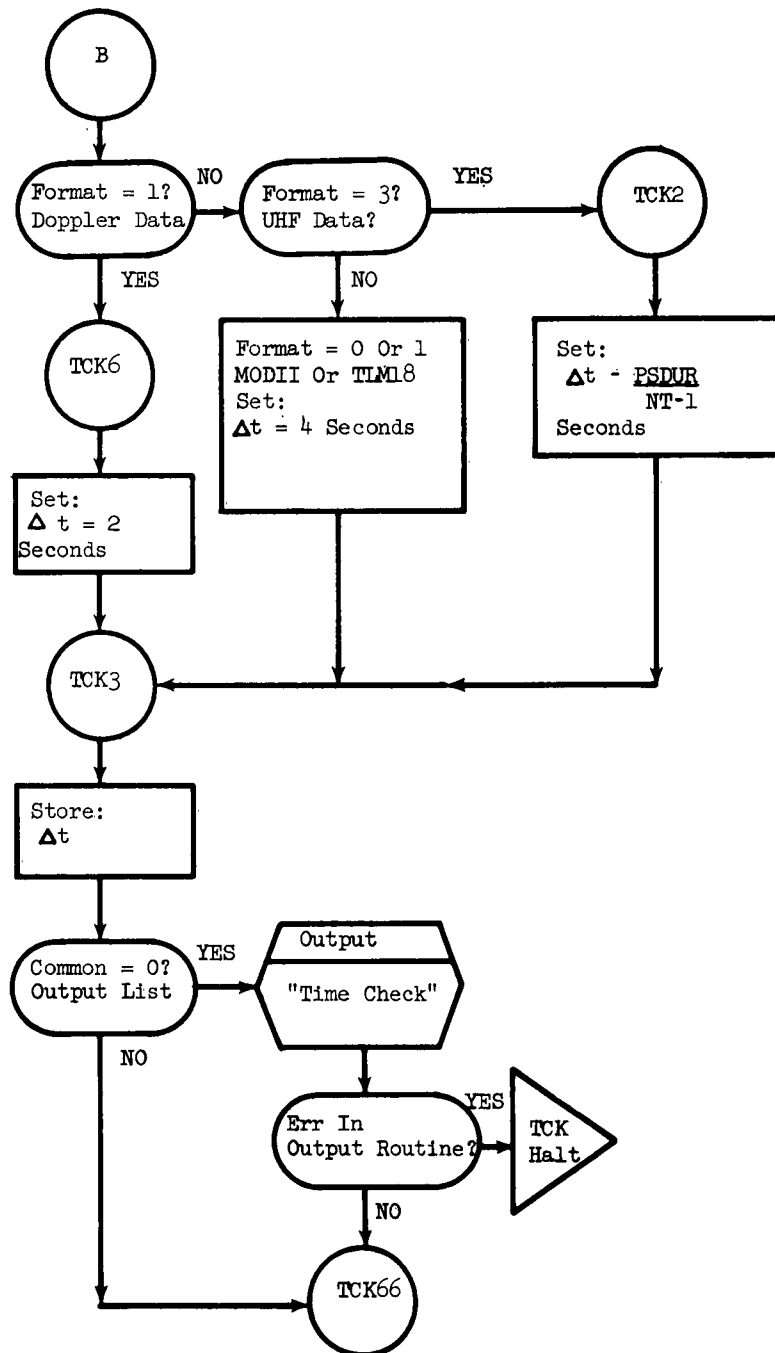


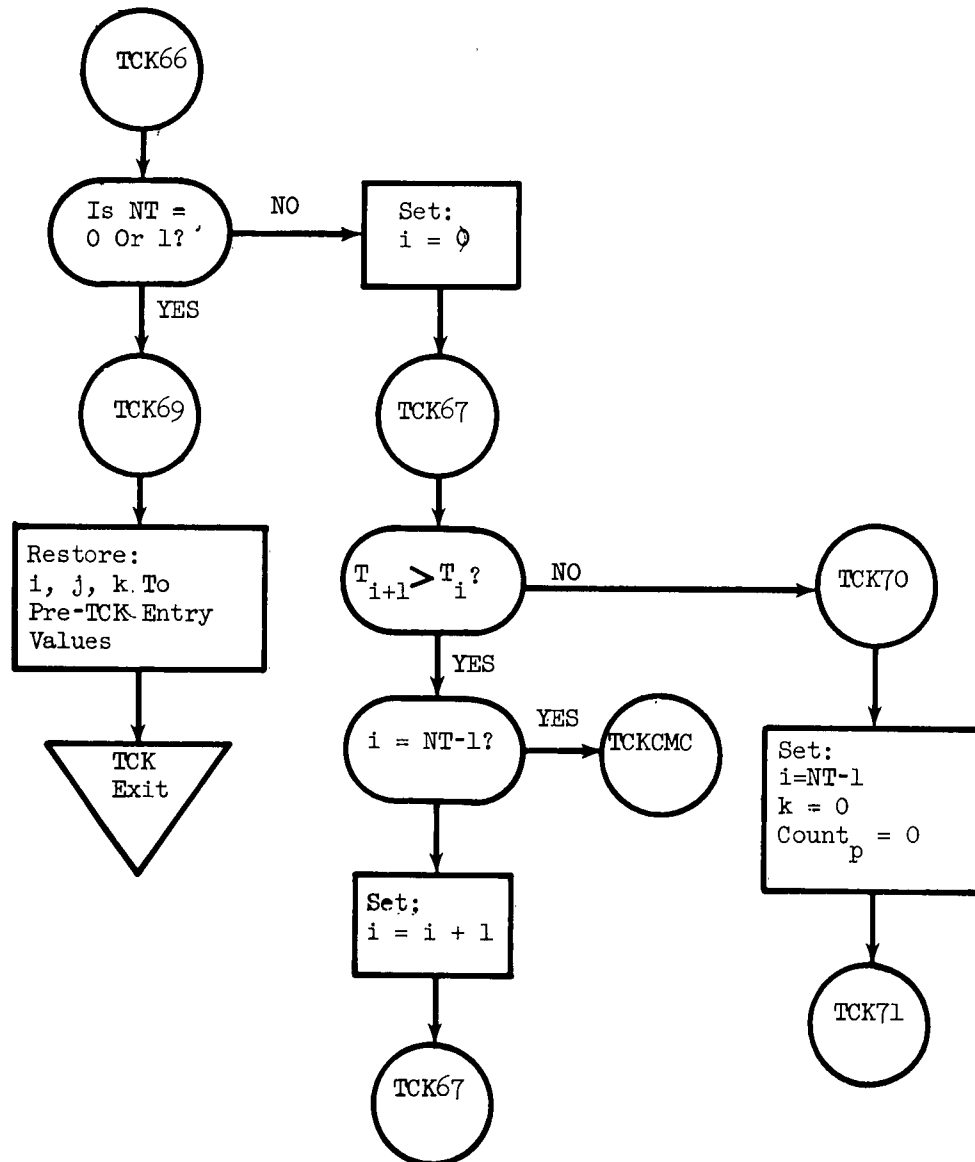
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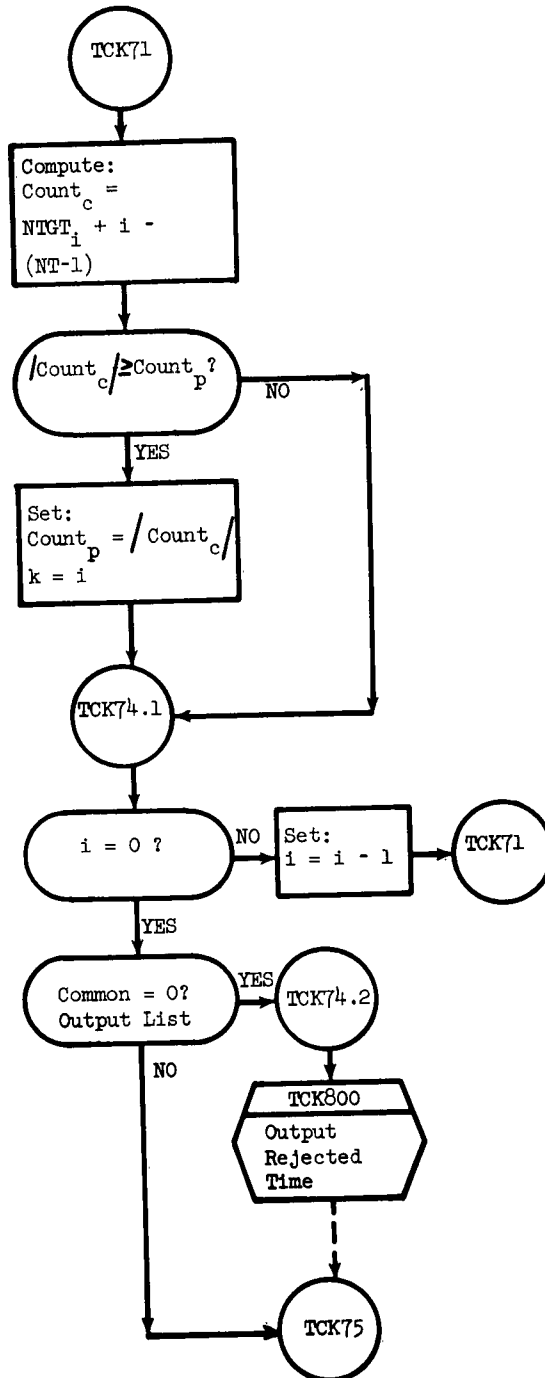


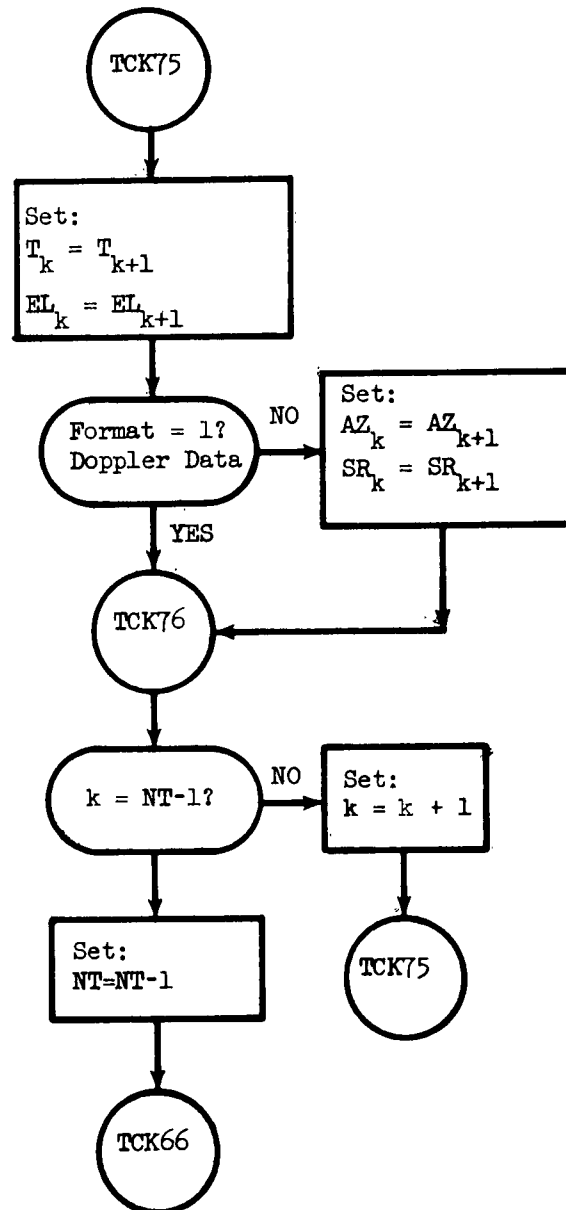


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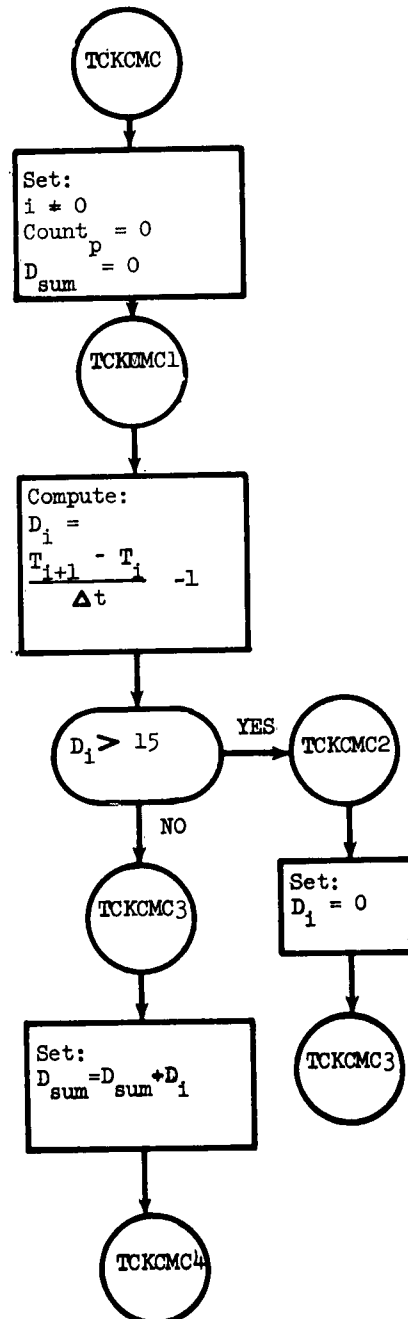




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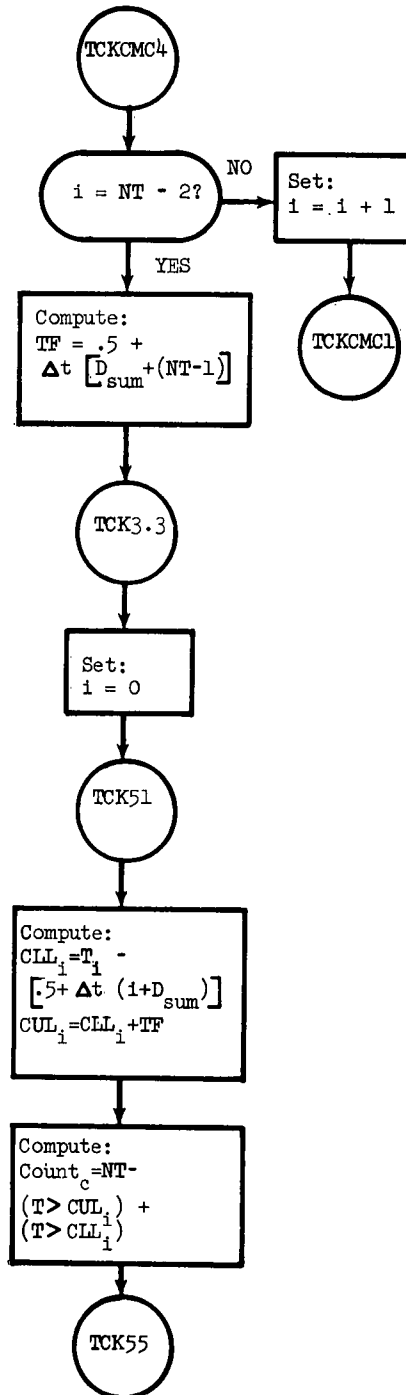
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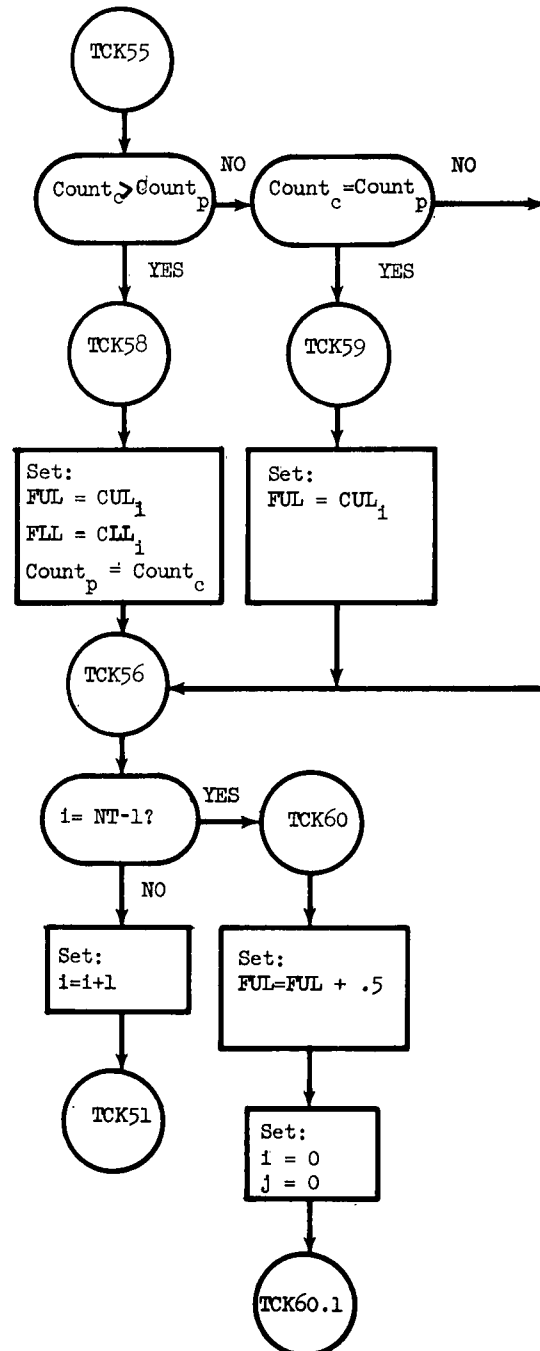


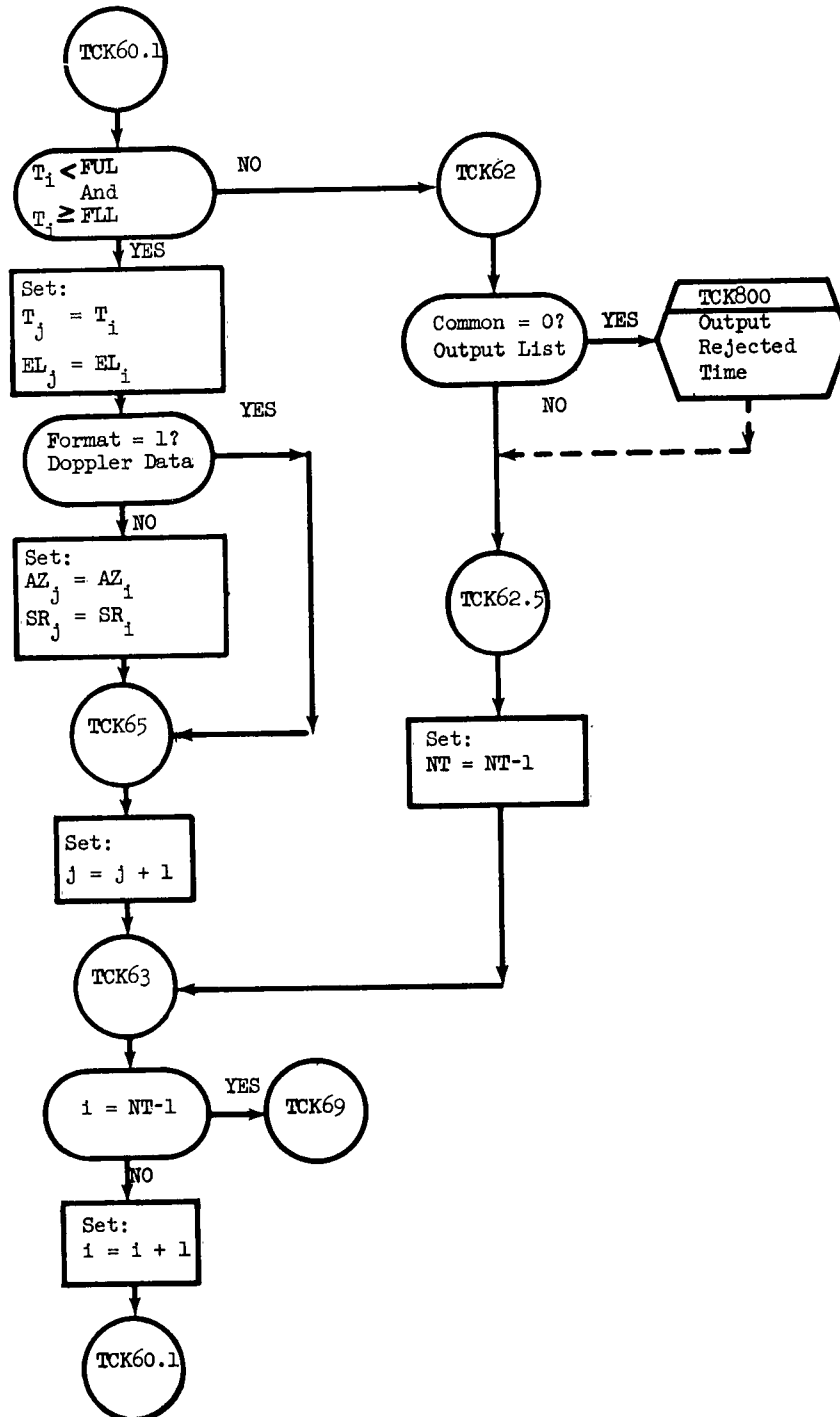
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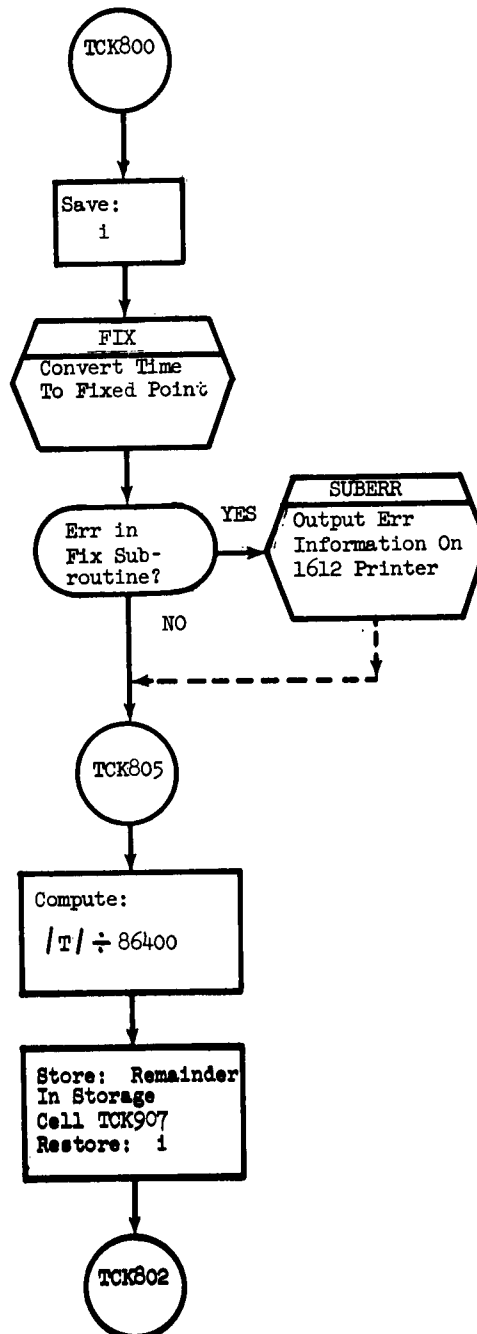




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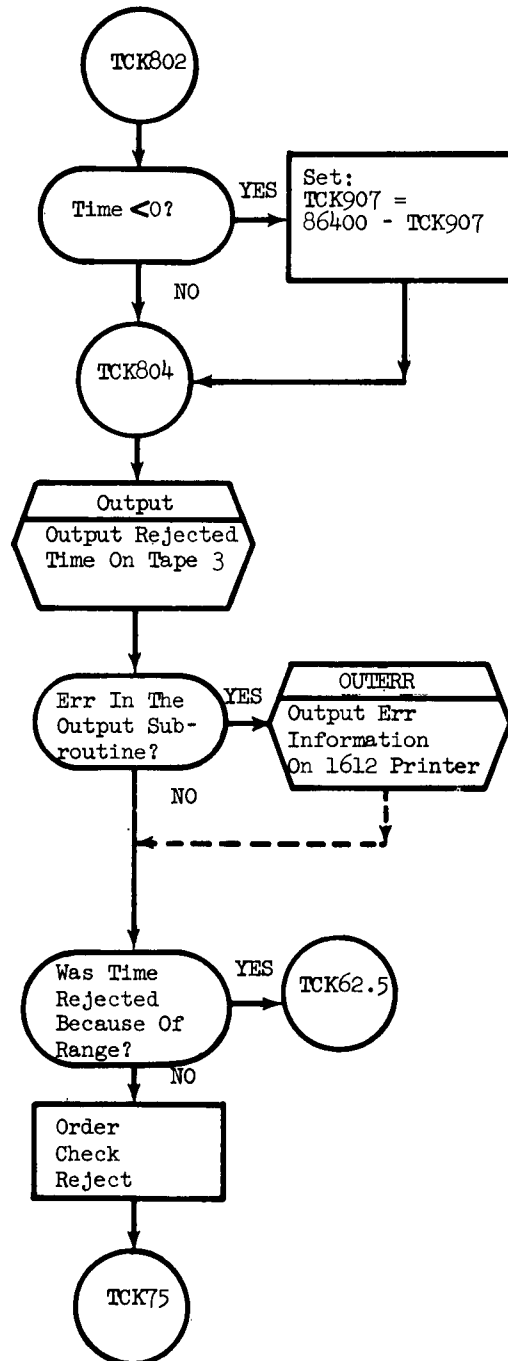
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System Development Corporation,  
Santa Monica, California  
GENERAL PURPOSE SATELLITE COMPUTER  
PROGRAM DESCRIPTIONS MILESTONE 11  
TIME CHECK (TCK).  
Scientific rept., TM(L)-714/012/00,  
by C. M. Chiodini. 14 November 1962,  
22p.  
(Contract AF 19(628)-1648, Space Systems  
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Division, AFSC)

Unclassified report

DESCRIPTORS: Satellite Networks.  
Programming (Computers).

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Reports that TCK (Time Check)  
deletes Tracking Data Points from  
the Constant Pool of the user  
function when the component times (T)  
are out of range or out of order.

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